

RT3000

Inertial and GPS Measurement System

Features

- 2 cm Positioning
- 0.05 km/h Velocity
- 10 mm/s² Acceleration
- Dual Antenna GPS
- 0.1° Heading
- 0.03° Roll, Pitch
- 0.15° Slip Angle
- 0.01°/s Angular Rates
- Other Measurements
- Real-Time
- Low Latency
- CAN Output
- Wheel speed input
- 2 GB Logging
- 5 min Installation
- Compact Size

Applications

- Photogrammetry
- Vehicle dynamics
- Autonomous vehicles
- AHRIS
- Video correction
- Road survey
- Aerial survey
- LIDAR correction

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RT3000 Inertial and Dual-GPS Navigation System

The RT3000 Inertial and Dual-GPS Navigation Systems are advanced six-axis inertial navigation systems, blended with precision GPS, to give robust outputs of position, orientation and velocity. The second GPS improves heading accuracy.

The RT3000 Inertial and GPS Navigation System includes three angular rate sensors (gyros), three servo-grade accelerometers, two GPS receivers and all the required processing in one very compact box.

Six dual GPS antenna models in the RT3000 family allow us to offer very competitively priced products. The difference between the products is the positioning performance of the GPS receiver, with our most accurate model offering 2cm accuracy.

The RT3000 works as a stand-alone, autonomous unit and

requires no user input before it starts operating.

The outputs from the RT3000 Inertial and GPS Navigation System are derived from the measurements of the accelerometers and gyros. Using the inertial sensors for the main outputs gives the RT3000 system a high update rate (100Hz) and a wide bandwidth. All the

outputs are computed in real-time with a very low latency.

The two GPS receivers work together to measure true heading. Unlike inertial navigation systems corrected by single antenna systems, the heading accuracy is constant and not dependent on having high dynamics. It is possible for the RT3000 to initialise without motion.

The RT3000 Inertial and GPS Navigation Systems outputs its real-time measurements over RS232, Ethernet and CAN bus.

The precision ADC in the RT3000 gives more than 20 bits of resolution. The resolution of the acceleration measurements is 0.12mm/s² (12µg). The ADC oversamples the analogue sensors and uses coning/sculling motion compensation algorithms to avoid aliasing of the signals.

The internal processing includes the strapdown algorithms (using a WGS-84 earth model), Kalman filtering and



RT3003 used for Aerial Survey Applications



Autonomous Vehicles



Vehicle Dynamics Testing

Parameter	RT3202	RT3102	RT3022	RT3003	RT3052	RT3042
Position Accuracy	3.0mCEP SPS	1.8mCEP SPS	1.8mCEP SPS	1.5mCEP SPS	1.8mCEP SPS	1.5mCEP SPS
	1.4mCEP SBAS	0.6mCEP SBAS	0.6mCEP SBAS	0.6mCEP SBAS	0.6mCEP SBAS	0.6mCEP SBAS
	1.0mCEP DGPS	0.4mCEP DGPS	0.4mCEP DGPS	0.4mCEP DGPS	0.4mCEP DGPS	0.4mCEP DGPS
			0.5mCEP VBS2	0.5mCEP VBS ²	0.5mCEP VBS ²	0.5mCEP VBS ²
			0.2m 1σ L1	0.15mCEP XP ²		0.15mCEP XP ²
				0.1mCEP HP ²		0.1mCEP HP ²
				0.2m 1σ L1		
				0.02m 1σ L1/L2		
Velocity Accuracy	0.2 km/h RMS	0.1 km/h RMS	0.08km/h RMS	0.05km/h RMS	0.08km/h RMS	0.07km/h RMS
Acceleration						
– Bias	10 mm/s ² 1σ	10 mm/s ² 1σ	10 mm/s ² 1σ	10 mm/s ² 1σ	10 mm/s ² 1σ	10 mm/s ² 1σ
– Linearity	0.01%	0.01%	0.01%	0.01%	0.01%	0.01%
– Scale Factor	0.1% 1σ	0.1% 1σ	0.1% 1σ	0.1% 1σ	0.1% 1σ	0.1% 1σ
– Range ¹	100 m/s ²	100 m/s ²	100 m/s ²	100 m/s ²	100 m/s ²	100 m/s ²
Roll/Pitch	0.1° 1σ	0.05° 1σ	0.04° 1σ	0.03° 1σ	0.04° 1σ	0.03° 1σ
Heading	0.2° 1σ	0.1° 1σ	0.1° 1σ	0.1° 1σ	0.1° 1σ	0.1° 1σ
Angular Rate						
– In-run Bias	2 deg/hr	2 deg/hr	2 deg/hr	2 deg/hr	2 deg/hr	2 deg/hr
– ARW	0.2 deg/√hr	0.2 deg/√hr	0.2 deg/√hr	0.2 deg/√hr	0.2 deg/√hr	0.2 deg/√hr
– Range ¹	100°/s	100°/s	100°/s	100°/s	100°/s	100°/s
Track (at 50km/h)	0.2° RMS	0.15° RMS	0.1° RMS	0.07° RMS	0.1° RMS	0.08° RMS
Slip Angle (at 50km/h)	0.3° RMS	0.2° RMS	0.15° RMS	0.15° RMS	0.15° RMS	0.15° RMS
Lateral Velocity	0.3%	0.2%	0.2%	0.2%	0.2%	0.2%

Note 1. 300m/s² and 300°/s options are available. Note 2. A subscription is required to use OmniStar VBS, XP and HP services.



Inertial Sensors in RT3000 include servo-grade accelerometers and precision MEMS angular rate sensors. Powerful 40MHz floating point DSP takes care of coning, sculling and aliasing.



Magnetic GPS antenna for vehicle mounting. Other types available.

in-flight alignment algorithms. The internal Pentium-class processor runs QNX real-time operating system to ensure that the outputs are always delivered on time.

The Kalman filter monitors the performance of the system and updates the measurements using GPS and wheel speed. By using the measurements from GPS, the RT3000 system is able to maintain highly accurate measurements and correct its inertial sensor errors.

The RT3000 comes with acquisition software that displays the data on a PC or on Pocket PC devices. The PC software can be used to save tests in files, display real-time results and monitor the performance.

The internal logging enables the RT3000 to work stand-alone. Post-mission, data can be output in ASCII text format and loaded in to the software of your choice.

Simple configuration software allows the user to change the mounting angle; displace the measurement point to a virtual location; change the differential GPS options, etc.

Models

To choose the best model for your application, think about the positioning accuracy you require and what differential GPS corrections you can supply. OmniStar systems give excellent results over a wide area. The RT3003 can give

more accurate positioning in a local area where licence-free radios can be used to transmit the corrections.

The RT3000 products are also available as single antenna models. For road vehicles the single antenna system may provide equally accurate measurements at a lower cost.

For further information please contact Oxford Technical Solutions or your nearest local agent.

Parameter	RT3000
Power	9-18 V d.c. 20 W
Dimensions (mm)	234 x 120 x 80
Weight	2.4 kg
Operating Temperature	-10 to 50°C
Shock Survival	100G, 11ms
Update Rate	100 Hz
Calculation Latency	3.5 ms
Internal Storage	2 GB